from gpiozero import Button
button = Button(4)
while True:
    if button.is_pressed:
        print("Button is pressed")
    else:
        print("Button is not pressed")

from gpiozero import MotionSensor
pir = MotionSensor(4)
while True:
    if pir.motion_detected:
        print("You moved")

from gpiozero import Motor
motor = Motor(forward=17, backward=18)
motor.forward()